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# The Synchronization Problem

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# Problem Statement

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Execute a discrete event simulation (DES) program on a parallel computer

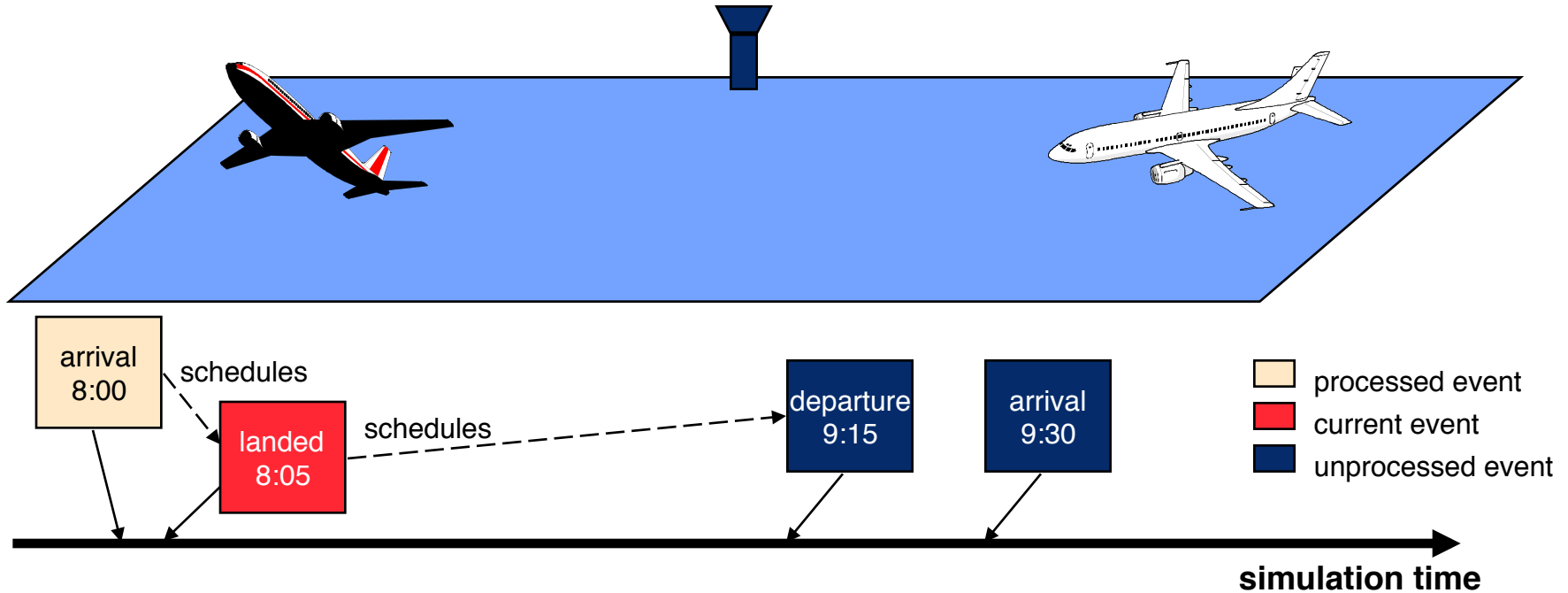
## Outline

- Start with a sequential DES
- Extend to a parallel simulation
- Synchronization problem
- Solution approaches
  - Conservative synchronization / Lookahead
  - Optimistic synchronization

# Example: Air Traffic Simulation

Air traffic at an airport; single runway for incoming flights

Aircraft arrive, queue to use runway, land, spend time at gate & depart



## Events

- Aircraft arrival
- Aircraft landed
- Aircraft departure

# Event-Oriented Sequential Simulation

## Event handler procedures

### state variables

```
Integer: InTheAir;  
Integer: OnTheGround;  
Boolean: RunwayFree;
```

```
Arrival  
Event
```

```
{
```

```
...
```

```
}
```

```
Landed  
Event
```

```
{
```

```
...
```

```
}
```

```
Departure  
Event
```

```
{
```

```
...
```

```
}
```

Simulation application

Simulation executive

Now = 8:45

Future Event List (FEL)

9:00

9:16

10:10

## Event processing loop

```
While (simulation not finished)
```

```
  E = smallest time stamp event in FEL
```

```
  Remove E from FEL
```

```
  Now := time stamp of E
```

```
  call event handler procedure
```

# Parallel Discrete Event Simulation

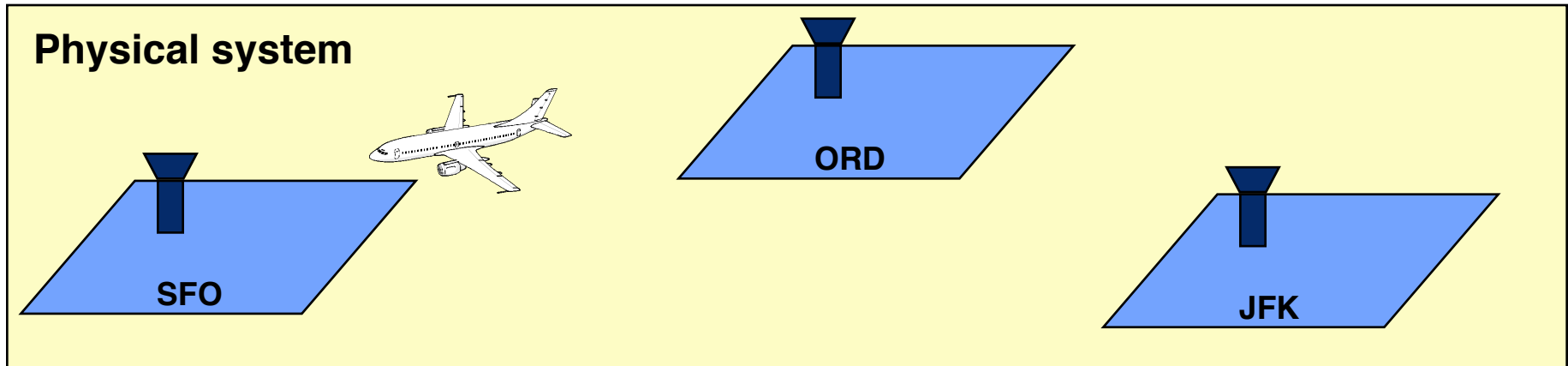
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- Example: model a network of airports
  - Encapsulate each airport simulator in a **logical process**
  - Logical processes can schedule events (**send messages**) for other logical processes

More generally...

- Physical system
  - Collection of interacting physical processes (airports)
- Simulation
  - Collection of logical processes (LPs)
  - Each LP models a physical process
  - Interactions between physical processes modeled by scheduling events between LPs

# Parallel Discrete Event Simulation Example



physical process

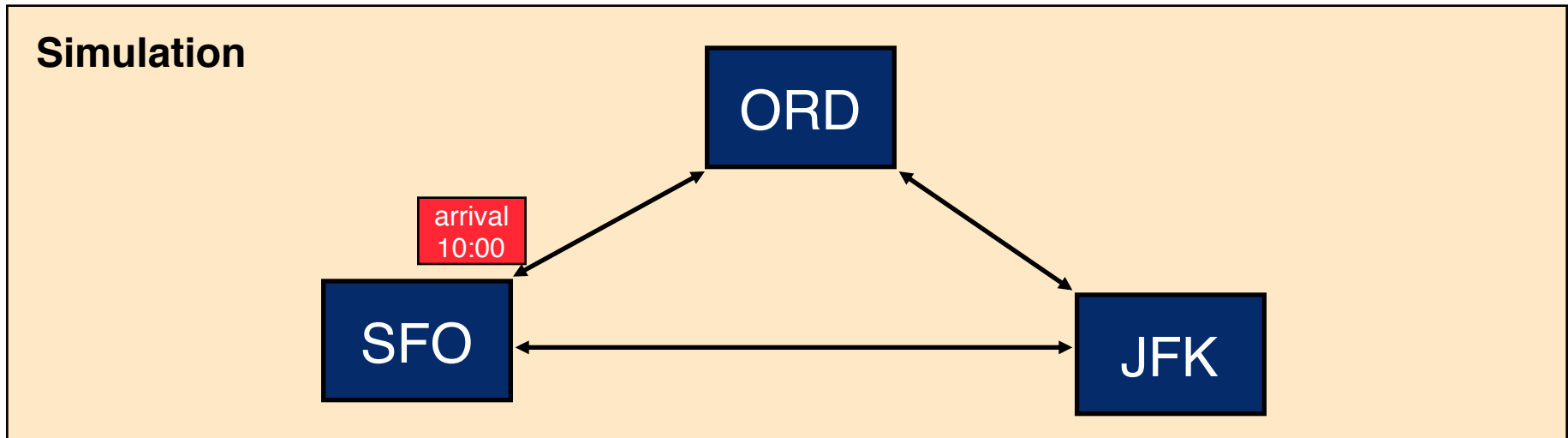


logical process

interactions among physical processes



time stamped event (message)



all interactions between LPs must be via messages (no shared state)

# LP Simulation Example

- Now: current simulation time
- InTheAir: number of aircraft landing or waiting to land
- OnTheGround: number of landed aircraft
- RunwayFree: Boolean, true if runway available

Arrival Event:

```
InTheAir := InTheAir+1;  
If (RunwayFree)  
    RunwayFree:=FALSE;  
    Schedule Landed event (local) @ Now+R;
```

Landed Event:

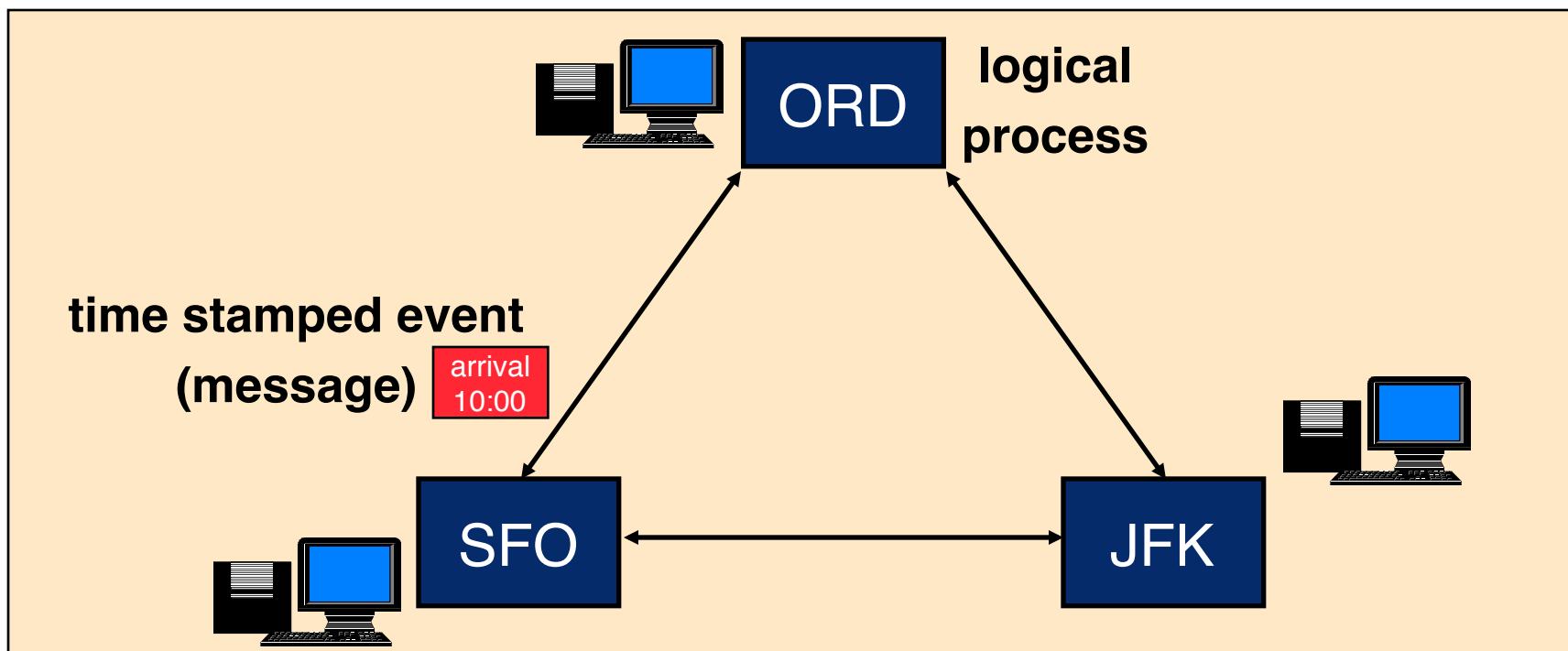
```
InTheAir:=InTheAir-1;      OnTheGround:=OnTheGround+1;  
Schedule Departure event (local) @ Now + G;  
If (InTheAir>0) Schedule Landed event (local) @ Now+R;  
Else RunwayFree := TRUE;
```

Departure Event (**D = delay to reach another airport**):

```
OnTheGround := OnTheGround - 1;  
Schedule Arrival Event (remote) @ (Now+D) @ another airport
```

# Approach to Parallel/Distributed Execution

- LP paradigm appears well suited to concurrent execution
- Map LPs to different processors
  - Multiple LPs per processor OK
- Communication via message passing
  - All interactions via messages
  - No shared state variables

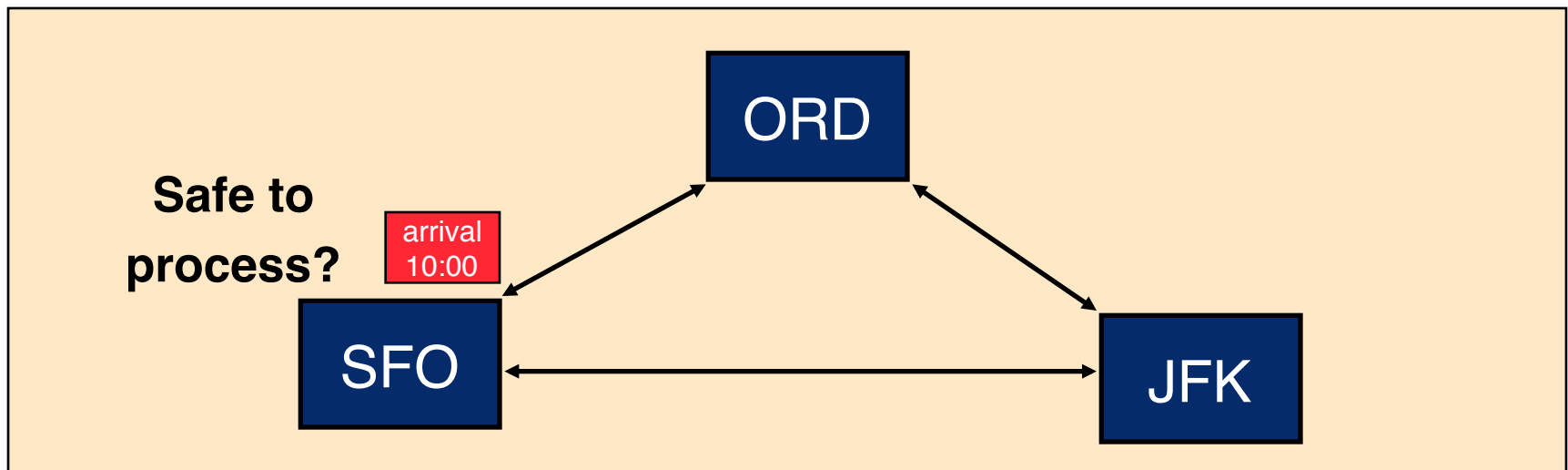




# The “Rub”

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Golden rule for each process: “Thou shalt process incoming messages in time stamp order” (**local causality constraint**)



# The Synchronization Problem

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Synchronization Problem: An algorithm is needed to ensure each LP processes events in time stamp order

Observation: ignoring events with the same time stamp, adherence to the local causality constraint is sufficient to ensure that the parallel simulation **will produce exactly the same results as a sequential execution** where all events across all LPs are processed in time stamp order.

# Synchronization Algorithms

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- Conservative synchronization: avoid violating the local causality constraint (wait until it's safe)
  - deadlock avoidance using null messages (Chandy/Misra/Bryant)
  - deadlock detection and recovery
  - synchronous algorithms (e.g., execute in “rounds”)
- Optimistic synchronization: allow violations of local causality to occur, but detect them at runtime and recover using a rollback mechanism
  - Time Warp (Jefferson)
  - numerous other approaches

# Summary

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- A parallel discrete event simulation can be viewed as a set of sequential discrete event simulations (logical processes) that exchange time-stamped events (messages)
- Each LP should process events in timestamp order
- This leads to the synchronization problem; solutions include conservative approaches that prevent LPs from processing events out of timestamp order to optimistic algorithms that detect out of order processing of events, and recover using a rollback mechanism