Discrete Event Simulation

Event-Oriented Simulation

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<u>Time</u>

- *physical system*: the actual or imagined system being modeled
- *simulation*: a system that emulates the behavior of a physical system



- physical time: time in the physical system
 - Noon, December 31, 1999 to noon January 1, 2000
- *simulation time:* representation of physical time within the simulation
 - floating point values in interval [0.0, 24.0]
- wallclock time: time during the execution of the simulation, usually output from a hardware clock
 - 9:00 to 9:15 AM on September 10, 1999

Simulation Time

Simulation time is defined as a totally ordered set of values where each value represents an instant of time in the physical system being modeled.

For any two values of simulation time T_1 representing instant P_1 , and T_2 representing P_2 :

- Correct ordering of time instants
 - If $T_1 < T_2$, then P_1 occurs before P_2
 - 9.0 represents 9 PM, 10.5 represents 10:30 PM
- Correct representation of time durations

 $-T_2 - T_1 = k (P_2 - P_1)$ for some constant k

- 1.0 in simulation time represents 1 hour of physical time

Paced vs. Unpaced Execution

Modes of execution

- As-fast-as-possible execution (unpaced): no fixed relationship necessarily exists between advances in simulation time and advances in wallclock time
- Real-time execution (paced): each advance in simulation time is paced to occur in synchrony with an equivalent advance in wallclock time
- Scaled real-time execution (paced): each advance in simulation time is paced to occur in synchrony with S * an equivalent advance in wallclock time (e.g., 2x wallclock time)

Simulation Time = $W2S(W) = T_0 + S * (W - W_0)$

W = wallclock time; S = scale factor

 $W_0(T_0) =$ wallclock (simulation) time at start of simulation (assume simulation and wallclock time use same time units)

Discrete Event Simulation

Discrete event simulation: computer model for a system where changes in the state of the system occur at *discrete* points in simulation time.

Fundamental concepts:

- system state (state variables)
- state transitions (events)

A DES computation can be viewed as a sequence of event computations, with each event computation is assigned a (simulation time) time stamp

Each event computation can

- modify state variables
- schedule new events

Discrete Event Simulation Computation



- Unprocessed events are stored in a pending event list
- Events are processed in time stamp order

Discrete Event Simulation System

model of the physical system

Simulation Application

- state variables
- code modeling system behavior
- I/O and user interface software

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independent of the simulation application

Simulation Executive

- event list management
- managing advances in simulation time

Event-Oriented World View



Simulation executive

Event processing loop



While (simulation not finished)
E = smallest time stamp event in PEL
Remove E from PEL
Now := time stamp of E
call event handler procedure

Example: Air traffic at an Airport

Model aircraft arrivals and departures, arrival queueing Single runway for incoming aircraft, ignore departure queueing

- R = time runway is used for each landing aircraft (constant)
- **G** = time required on the ground before departing (constant)

State:

- Now: current simulation time
- InTheAir: number of aircraft landing or waiting to land
- OnTheGround: number of landed aircraft
- RunwayFree: Boolean, true if runway available

Events:

- Arrival: denotes aircraft arriving in air space of airport
- Landed: denotes aircraft landing
- Departure: denotes aircraft leaving

Arrival Events

New aircraft arrives at airport. If the runway is free, it will begin to land. Otherwise, the aircraft must circle, and wait to land.

- \mathbf{R} = time runway is used for each landing aircraft
- G = time required on the ground before departing
- Now: current simulation time
- InTheAir: number of aircraft landing or waiting to land
- OnTheGround: number of landed aircraft
- RunwayFree: Boolean, true if runway available

```
Arrival Event:
```

InTheAir := InTheAir+1;

If (RunwayFree)

```
RunwayFree:=FALSE;
```

Schedule Landed event @ Now + R;

Landed Event

An aircraft has completed its landing.

- **R** = time runway is used for each landing aircraft
- G = time required on the ground before departing
- Now: current simulation time
- InTheAir: number of aircraft landing or waiting to land
- OnTheGround: number of landed aircraft
- RunwayFree: Boolean, true if runway available

```
Landed Event:
InTheAir:=InTheAir-1;
OnTheGround:=OnTheGround+1;
Schedule Departure event @ Now + G;
If (InTheAir>0)
Schedule Landed event @ Now + R;
Else
RunwayFree := TRUE;
```

Departure Event

An aircraft now on the ground departs for a new destination.

- \mathbf{R} = time runway is used for each landing aircraft
- G = time required on the ground before departing
- Now: current simulation time
- InTheAir: number of aircraft landing or waiting to land
- OnTheGround: number of landed aircraft
- RunwayFree: Boolean, true if runway available

```
Departure Event:
```

```
OnTheGround := OnTheGround - 1;
```

Execution Example



Summary

• Time

- Important to distinguish among simulation time, wallclock time, and time in the physical system
- Paced execution (e.g., immersive virtual environments) vs. unpaced execution (e.g., simulations to analyze systems)
- DES computation: sequence of event computations
 - Modify state variables
 - Schedule new events
- DES System = model + simulation executive
- Data structures
 - Pending event list to hold unprocessed events
 - State variables
 - Simulation time clock variable
- Program (Code)
 - Main event processing loop
 - Event procedures
 - Events processed in time stamp order